**Optimal N-Queens**

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| **Search** | **Number of Failures** | **Objective Value** |
| def | 5,735,329 | 796 |
| dWd-rand | 11,617,849 | 790 |
| dWd-rand + restart | 5,949,412 | 676 |
| dWd-rand + restart + LNS | 1,853,636 | 650 |

The table above shows the number of failures and the corresponding objective values related to the type of search performed.

We started with a "default" search and gradually added elements to improve the objective value.

Let's go through each step specifically:

1. **def -> dWd-rand:** the dWd strategy manages to achieve a better final result because it identifies in advance the queens that are more likely to fail and places them first. It is worth noting that in the second case, we have a higher number of failures. This is justified by the fact that dWd-rand allows failures to occur as early as possible without necessarily reaching blind spots in the tree. This way, it can explore the tree more rapidly, evaluating more branches and therefore experiencing more failures. The reason for this increase is that by imposing a maximum time limit, the second strategy evaluates more branches of the tree within that time, finding more failures.
2. **dWd**-**rand -> dwd-rand+restart:** Conducting the search by restarting the solver leads to an improvement due to the retention of some information obtained during the previous executions.
3. **dwd**-**rand+restart -> dwd-rand + restart + LNS:** Here, we observe an improvement due to the fact that, given the high number of fixed variables, this should be the reason for the lower number of failures. The remaining variables are simpler to explore, as well as the constraint propagation.